

Electromagnetic Theory: PHAS3201, Winter 2008

5. Maxwell's Equations and EM Waves

1 Displacement Current

We already have most of the pieces that we require for a full statement of Maxwell's Equations; however, we have not considered the full derivation of all components. In particular, when considering magnetic fields, we mentioned that it is important to account for time-varying electric fields in Ampere's law. We will consider in detail where this requirement comes from, and how it can be understood from the continuity equation.

Correcting Ampère

- Consider a capacitor charging with a current, I
- Ampere's law in the *original* form gives:

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 \int_S \mathbf{J} \cdot \mathbf{n} da \quad (1)$$

- Take a loop, C , around the wire to the left plate
- Also consider two different surfaces:
 1. A surface cutting the wire (co-planar with C)
 2. A surface not cutting the wire (away from C)
- These will give two different answers
- For 1, we find I , while for 2, we find zero

TAKE NOTES

2 Maxwell's Equations

We state Maxwell's equations in differential and integral form, and derive a wave equation for \mathbf{H} and \mathbf{E} , generalising for linear, isotropic materials.

Differential Form

- We can now state the full set of Maxwell's equations

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \quad (\text{Ampère-Maxwell}) \quad (2)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (\text{Faraday}) \quad (3)$$

$$\nabla \cdot \mathbf{D} = \rho \quad (\text{Coulomb-Gauss}) \quad (4)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (\text{Biot-Savart+}) \quad (5)$$

Integral Form

- In integral form (for completeness):

$$\oint_C \mathbf{H} \cdot d\mathbf{l} = \int_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot \mathbf{n} da \quad (6)$$

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = - \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot \mathbf{n} da = - \frac{d\Phi}{dt} \quad (7)$$

$$\oint_S \mathbf{D} \cdot \mathbf{n} da = \int_v \rho dv \quad (8)$$

$$\oint_S \mathbf{B} \cdot \mathbf{n} da = 0 \quad (9)$$

Wave Equations

- We now want to *solve* for the electric and magnetic fields
- We need to find an equation for *each* variable
- Assume a uniform, linear, isotropic medium
- Then $\mathbf{D} = \epsilon \mathbf{E}$ and $\mathbf{B} = \mu \mathbf{H}$
- We start with the Ampère-Maxwell equation
- We also assume that the medium has uniform conductivity g , so that $\mathbf{J} = g \mathbf{E}$

TAKE NOTES

Equation for H

- We find that:

$$\nabla^2 \mathbf{H} - g\mu \frac{\partial \mathbf{H}}{\partial t} - \epsilon\mu \frac{\partial^2 \mathbf{H}}{\partial t^2} = 0 \quad (10)$$

- This is a wave equation for \mathbf{H} , with damping proportional to $g\mu$
- A finite resistance dissipates energy (e.g. metal, plasma)
- As $g \rightarrow 0$ (a non-conducting medium), we recover:

$$\nabla^2 \mathbf{H} = \epsilon\mu \frac{\partial^2 \mathbf{H}}{\partial t^2} \quad (11)$$

- Repeat the procedure for Faraday's law

TAKE NOTES

Equation for E

- We find that:

$$\nabla^2 \mathbf{E} - g\mu \frac{\partial \mathbf{E}}{\partial t} - \epsilon\mu \frac{\partial^2 \mathbf{E}}{\partial t^2} = 0 \quad (12)$$

- This is a wave equation for \mathbf{E} ; as before, if $g \rightarrow 0$ we find:

$$\nabla^2 \mathbf{E} = \epsilon\mu \frac{\partial^2 \mathbf{E}}{\partial t^2} \quad (13)$$

- Notice that the speed of the wave is $c = 1/\sqrt{\epsilon\mu}$
- We can get equations for \mathbf{D} and \mathbf{B} from linearity
- The solutions will be plane waves:

$$\mathbf{H}(\mathbf{r}, t) = \mathbf{H}_0 e^{i(\mathbf{k}_H \cdot \mathbf{r} - \omega_H t)} \quad (14)$$

3 Plane Waves

One general note: you will find that people use i and j to represent $\sqrt{-1}$ indiscriminately. Mainly engineers use j , but you cannot guarantee this ! Be on your guard.

Solution for \mathbf{H}

- Assume that $\mathbf{k} = (0, 0, k)$ lies along z-axis
- $\nabla^2 \mathbf{H} = -k^2 \mathbf{H}$
- $\partial^2 \mathbf{H} / \partial t^2 = -\omega^2 \mathbf{H}$
- As we expect, we see that if $k^2 / \omega^2 = \epsilon \mu$, then a plane wave solves the equation for \mathbf{H}
- The phase velocity is $c = 1 / \sqrt{\epsilon \mu}$
- Faraday's law links \mathbf{E} and \mathbf{B} : how are the solutions linked ?

TAKE NOTES

Electromagnetic Waves

- To fulfil Faraday's law, we have $\mathbf{k}_B = \mathbf{k}_E = \mathbf{k}$
- Also $\omega_B = \omega_E = \omega$ and $\phi_B = \phi_E = \phi$
- Then the link between electric and magnetic fields is:

$$\mathbf{k} \times \mathbf{E}_0 = \omega \mathbf{B}_0 \quad (15)$$

- \mathbf{k} lies *along* the direction of propagation

Illustration

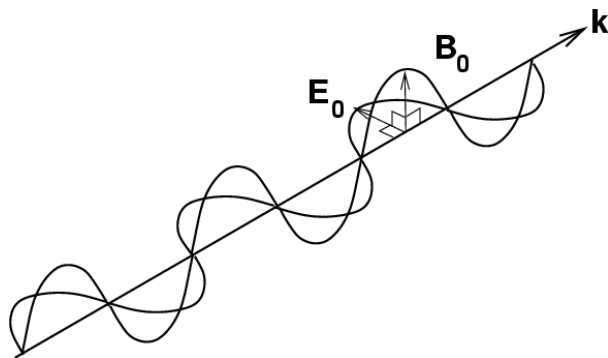


Figure 1: A linearly polarised or plane-polarised electromagnetic plane wave

- \mathbf{B} is perpendicular to \mathbf{k} , \mathbf{E}
- Since $\nabla \cdot \mathbf{E} = i\mathbf{k} \cdot \mathbf{E} = 0$, \mathbf{k} & \mathbf{E} are perpendicular
- A transverse electric & magnetic wave (TEM)

TAKE NOTES

4 Polarisation

\mathbf{E}_0

- We have discussed a *special* case: plane or linearly polarised light
- In general, \mathbf{E}_0 is complex and has freedom
- We assume propagation along z-axis, $\mathbf{k} = (0, 0, k)$
- E_x & E_y have independent amplitude and phase

$$\mathbf{E}_0 = E_{0x}e^{i\phi_x}\mathbf{i} + E_{0y}e^{i\phi_y}\mathbf{j} \quad (16)$$

- We can write $\mathbf{E} = \mathbf{E}_0 e^{i(kz - \omega t)}$
- How do the different components relate ?

TAKE NOTES

Phase Relation

- The real part of \mathbf{E} is:

$$\begin{aligned} \mathbf{E}_{Re} = & \cos(kz + \phi_x) (E_{0x} \cos(\omega t) \mathbf{i} + E_{0y} \cos(\omega t - \phi) \mathbf{j}) \\ & + \sin(kz + \phi_x) (E_{0x} \sin(\omega t) \mathbf{i} - E_{0y} \sin(\omega t - \phi) \mathbf{j}) \end{aligned} \quad (17)$$

- The *phase difference* between E_{0x} & E_{0y} is ϕ
- The tip of the field vector follows a spiral

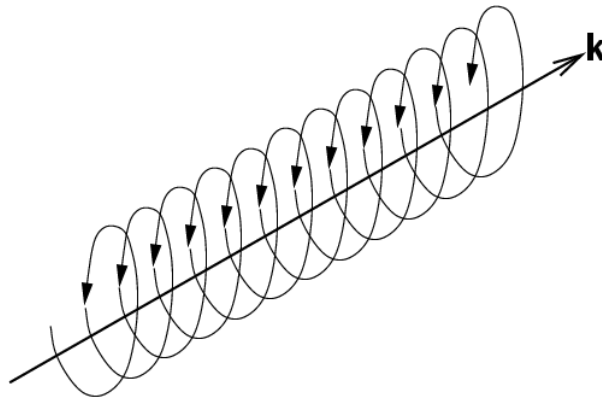


Figure 2: The path traced by the tip of electric field vector of an elliptically polarised electromagnetic plane wave

Types

- $\phi = 0$ or π : plane or linear polarisation
- $\phi = \pi/2$ or $3\pi/2$ with $E_{0x} = E_{0y}$: circular polarisation
- $E_{0x} \neq E_{0y}$, $\phi \neq 0$: elliptical polarisation

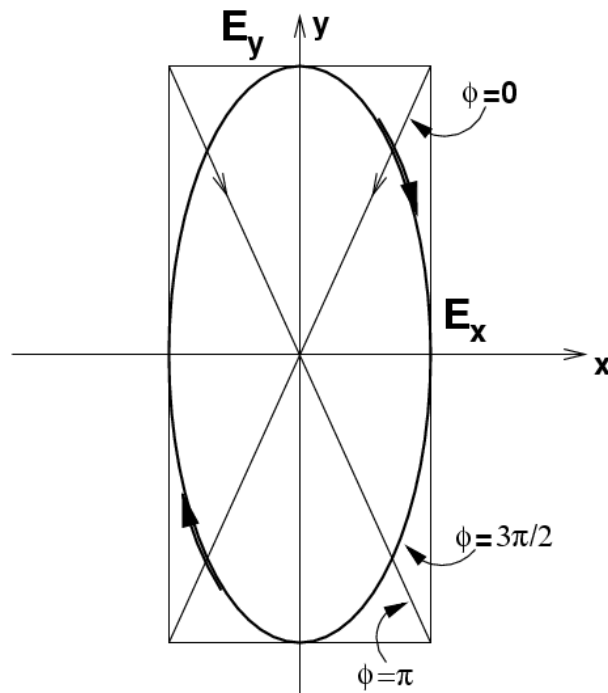


Figure 3: The path traced by the tip of the electric field vector at a given plane in space over time for elliptical polarisation; the propagation is out of the page.

Types

- If $E_{0x} \neq E_{0y}$ for plane polarisation, then the plane is at an angle $\theta = \tan^{-1}(E_{y0}/E_{x0})$
- Unpolarised light has the polarisation varying randomly with time (only possible for spectral continuum)
- “Ordinary” light sources (e.g. light bulb, sun) give this
- Partially polarised light is a mix of specific kinds, or light which has had a plane *imposed* (e.g. using Polaroid filter)
- Basic property is the relation of the x and y vectors in the field